

Stationary Shear Flow of Granular Matter, a tentative continuum modelling

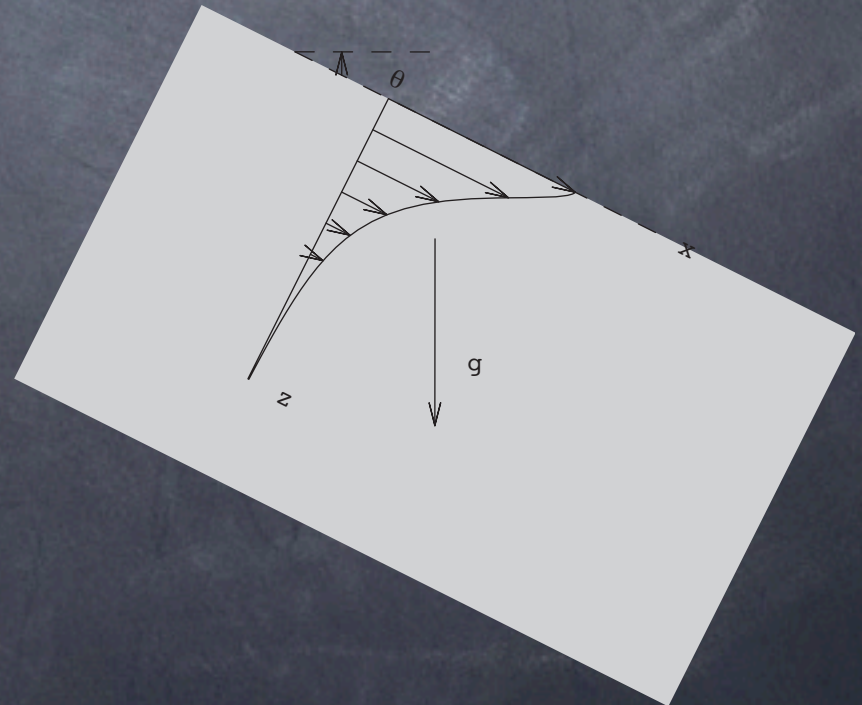
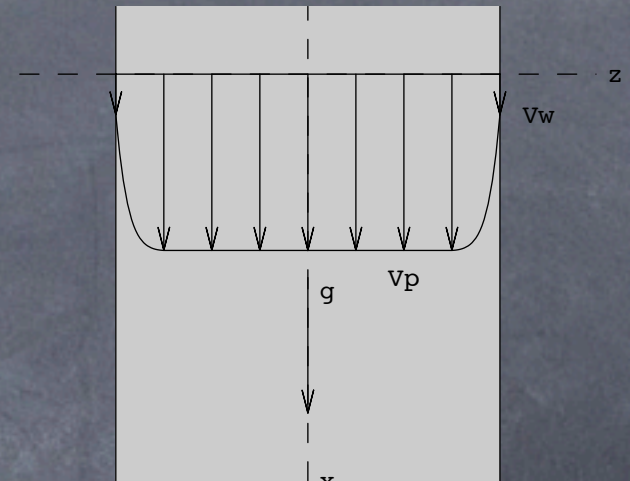
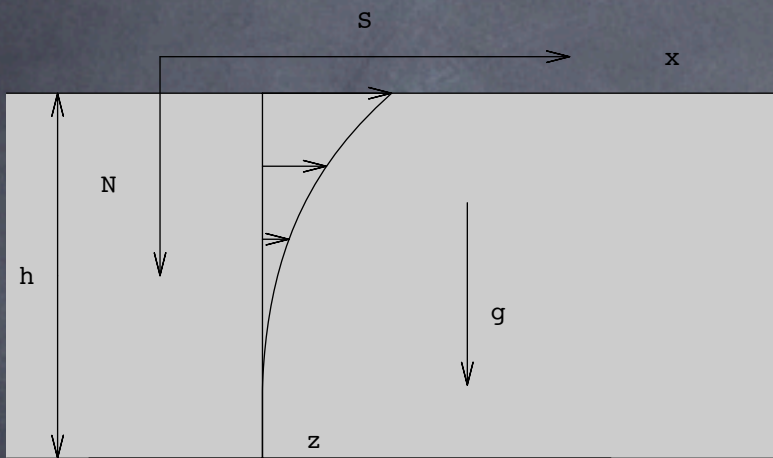
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Topics

- Role of solid fraction
- Dry granular materials
- 2D steady shear flow
- main ingredients
 - solid fraction
 - dilatancy
 - granular pressure
 - Bagnold/ Coulomb
- Continuum mechanical model
- Predictions
 - free surface flows
 - confined flows



Shear Flows



Solid Volume fraction ϕ

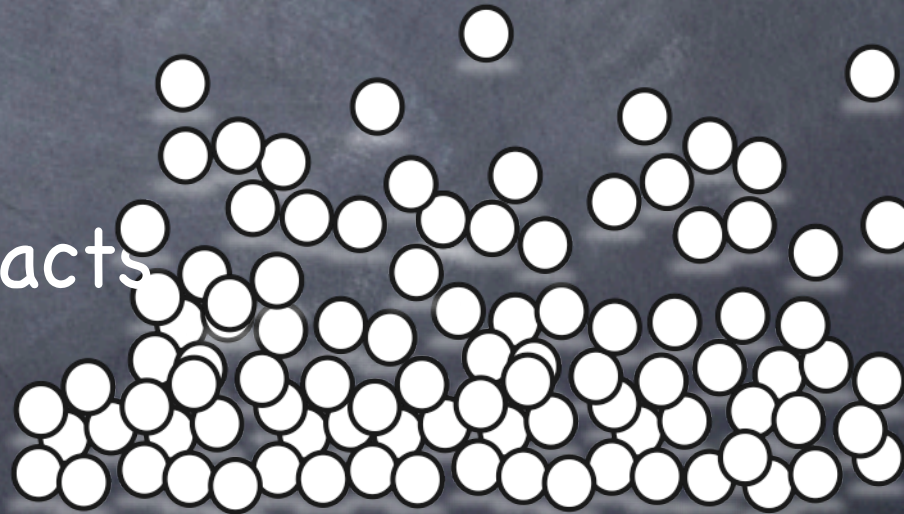
0.5 (2D) 0.55 (3D) $\phi_{min} < \phi < \phi_{Max}$ 0.8 (2D) 0.65 (3D)

suspensions

impacts

granular matter long lived contacts

solid-like matter elastic forces



Dry Granular Matter

$$\phi_{min} < \phi < \phi_{Max}$$

no interstitial fluid/ no cohesive forces

granular stress τ

static

$$\tau = \text{contact stress}(\varepsilon, \phi_s)$$

pseudo static preparation dependent

flow

$$\tau = \text{contact pressure}(\phi)$$

+rate-dep. stress($\phi, (\nabla V)^S, \omega - \frac{1}{2}\nabla \times V$)

fully tensorial relation: too difficult!!!
simple 2D steady flows...

rotation

- Assumption: rotation = vorticity

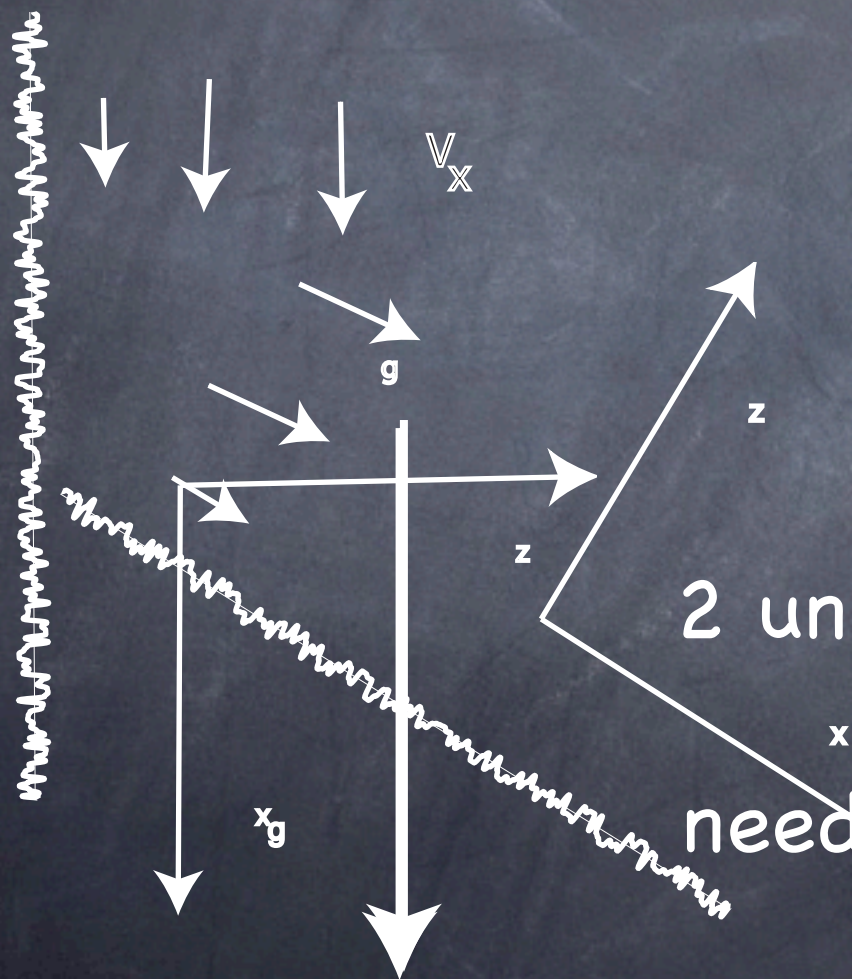
$$\omega = \frac{1}{2} \nabla \times V$$

Warning ! Possible failure close to rough boundaries

compression z

flow x

granular stress τ balance of forces



$$\frac{\partial \tau_{xz}}{\partial z} + \phi \rho g \sin(\theta) = 0$$

$$\frac{\partial \tau_{zz}}{\partial z} - \phi \rho g \cos(\theta) = 0$$

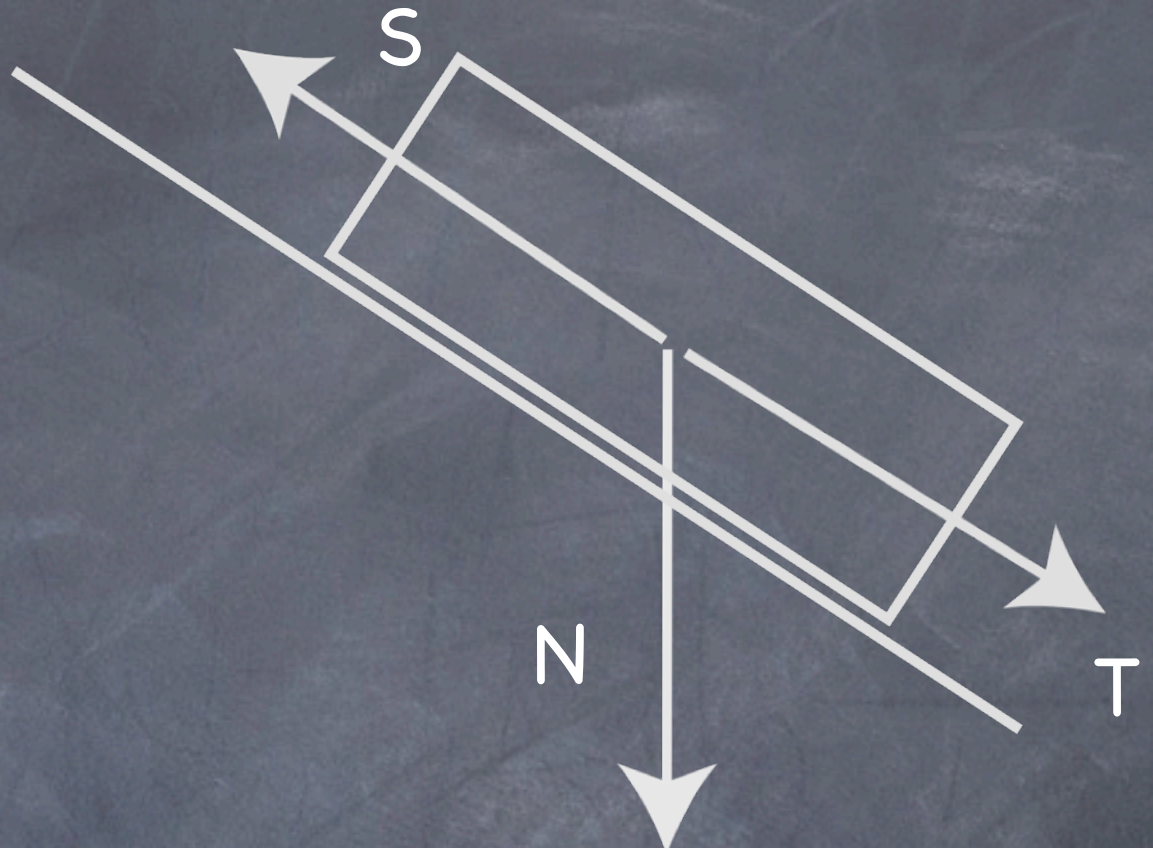
2 unknowns

ϕ and $\frac{\partial V_x}{\partial z}$

need for: $\tau_{zz}(\phi, \frac{\partial V_x}{\partial z})$ and $\tau_{xz}(\phi, \frac{\partial V_x}{\partial z})$

Warning ! Possible failure close to rough boundaries

Solid Friction



$$S = \mu N \quad \text{motion}$$

present model:
at incipient motion

$$\tau_{xz} = \mu(\phi) \tau_{zz}$$

present model:
Bagnold Scaling is only part of the stress

$$\begin{matrix} \tau_{zz} \\ \tau_{xz} \end{matrix} \quad \begin{matrix} / \\ \backslash \end{matrix} \quad \rho D^2 \left(\frac{\partial V_x}{\partial z} \right)^2$$

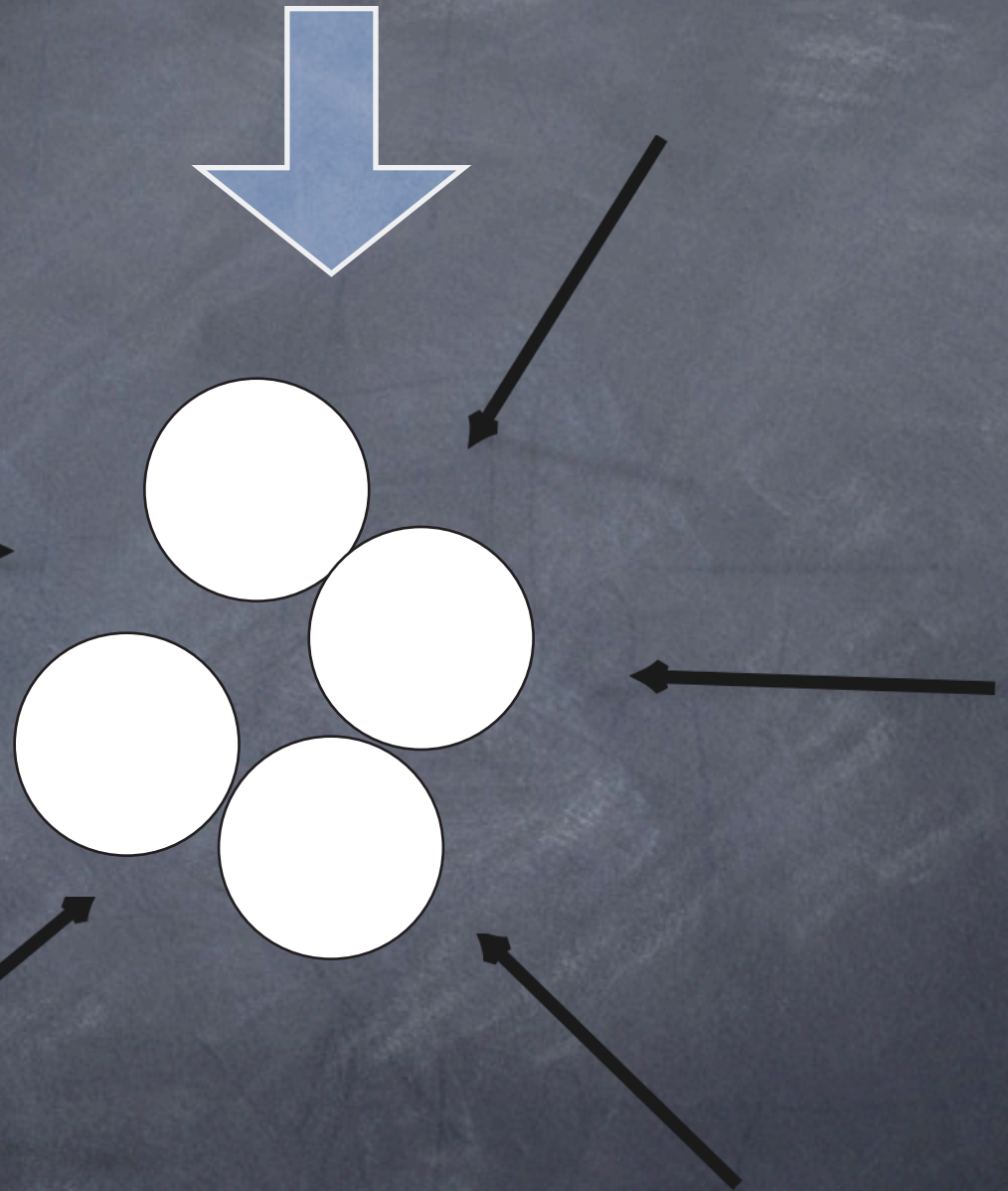
Contact Pressure

normal stress

compaction ϕ_s

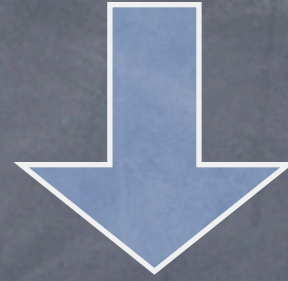
normal stress step ΔN

elastic deformation
sliding contacts
relax. of elastic def.



$$\tau_{zz} = \rho g DF(\phi)$$

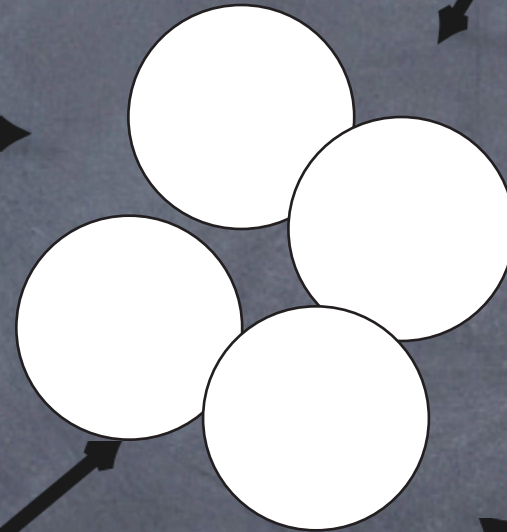
Contact Pressure



normal stress step ΔN

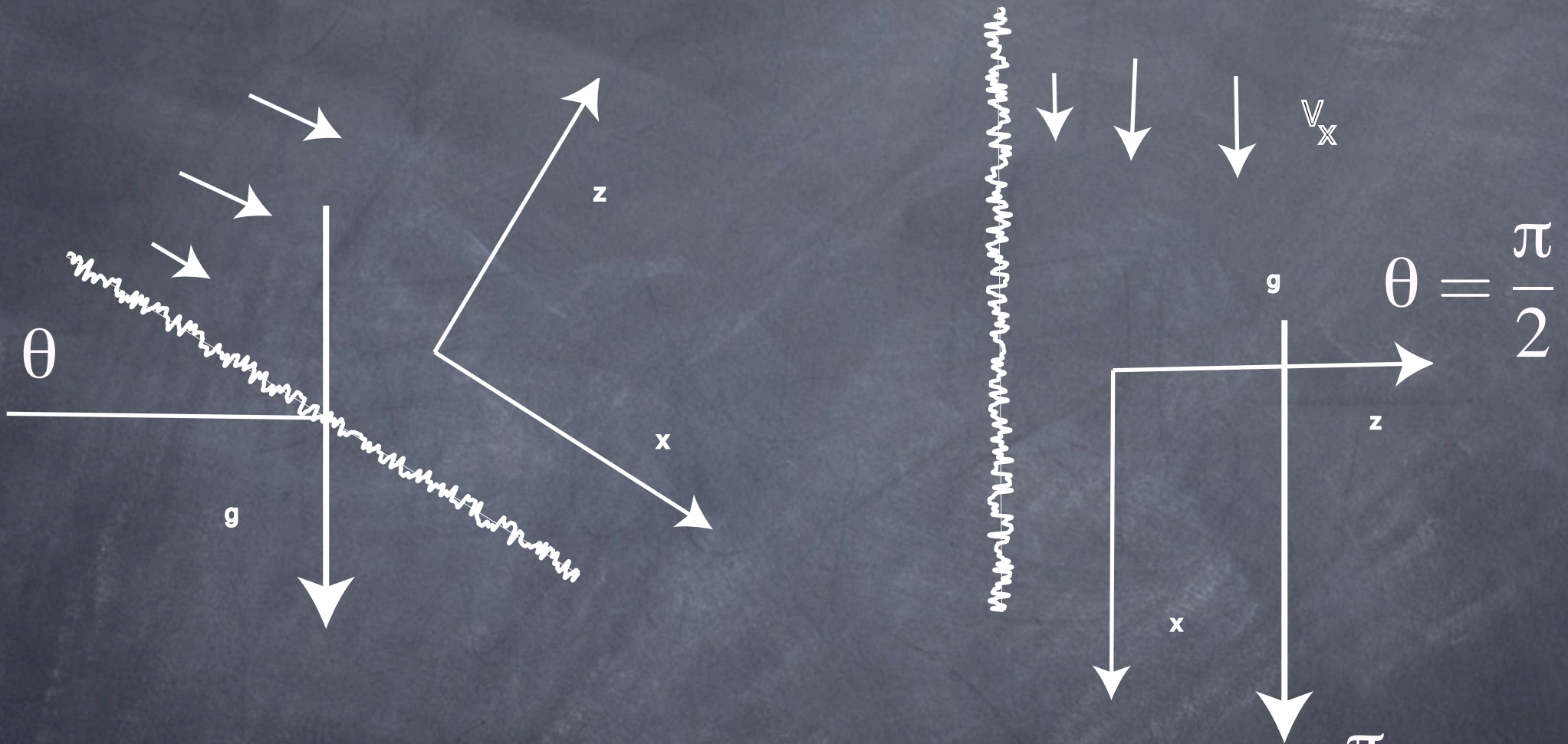
elastic deformation
sliding contacts
relax. of elastic def.

Normal stress $N + \Delta N$
compaction $\phi + \Delta\phi$



$$\tau_{zz} = \rho g DF(\phi)$$

gravity induced compressive stress



$$\tau_{zz} = \rho g D F(\phi) f(\theta) \text{ with } f(0) = 1 \text{ and } f\left(\frac{\pi}{2}\right) = 0$$

$$\tau_{zz} = \rho g D F(\phi) \cos(\theta)$$

constitutive relations

• Normal stress

$$\tau_{zz} = \rho g D F(\phi) \cos(\theta) + \rho D^2 \mu_N(\phi) \left(\frac{\partial V_x}{\partial z} \right)^2$$

• shear stress $\tau_{xz} = \mu(\phi) \tau_{zz} + \rho D^2 \mu_T(\phi) \left(\frac{\partial V_x}{\partial z} \right)^2$

Equations of motion

$$\frac{\partial \tau_{xz}}{\partial z} + \phi \rho g \sin(\theta) = 0$$

$$\frac{\partial \tau_{zz}}{\partial z} - \phi \rho g \cos(\theta) = 0$$

for given F, μ, μ_N, μ_T , we obtain $\phi(z)$ and $V_x(z)$

solution:

$$D \frac{d\phi}{dz} = \frac{\phi}{\frac{\partial}{\partial \phi} \left[\frac{F}{1 - (\mu_N/\mu_T)(\tan(\theta) - \mu)} \right]}$$

$$\left(\frac{D}{g} \right)^{1/2} \frac{dV}{dz} = - \left(\frac{F(\sin(\theta) - \mu \cos(\theta))}{\mu_T(1 - (\mu_N/\mu_T)(\tan(\theta) - \mu))} \right)$$

$$\mu(\phi) \leq \tan(\theta) \leq \mu(\phi) + \mu_T(\phi)/\mu_N(\phi)$$

special model

μ and μ_T/μ_N independant of compaction

$$F = F_0 \text{Log} \left(\frac{\phi_M - \phi_m}{\phi_M - \phi} \right) \text{ and } \mu_T = \mu_{T0} \left(\frac{\phi_M - \phi_m}{\phi_M - \phi} \right)^2$$

Allows numerical computation

Special Form of F

- like entropy for lattice gaz

$$F = F_0 \text{Log} \left(\frac{\phi_M - \phi_m}{\phi_M - \phi} \right)$$

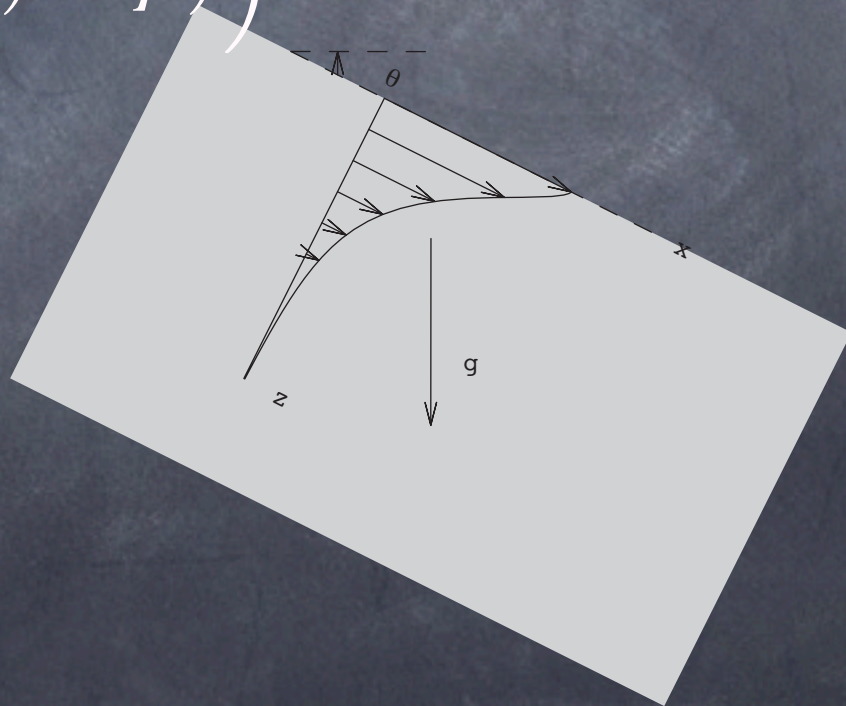
explicit expression

$$\phi_{heap}(z, \theta) = \frac{\phi_M}{1 + \left(\frac{\phi_M}{\phi_m} - 1\right)e^{-z/L(\theta)}}$$

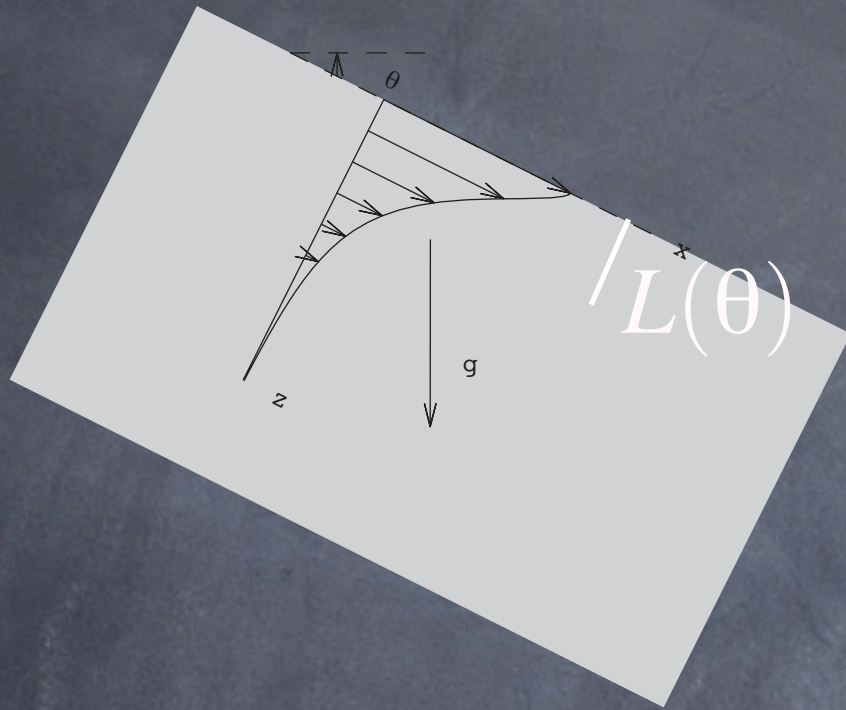
$$L(\theta) = \frac{F_0 D}{\phi_M \left(1 - \frac{\mu_N}{\mu_T} (\tan(\theta) - \mu)\right)}$$

Heap Flow

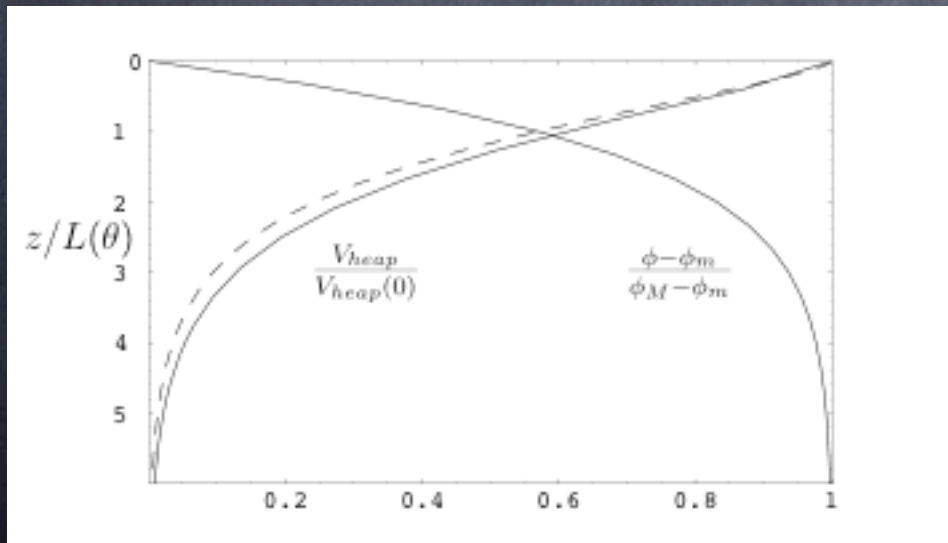
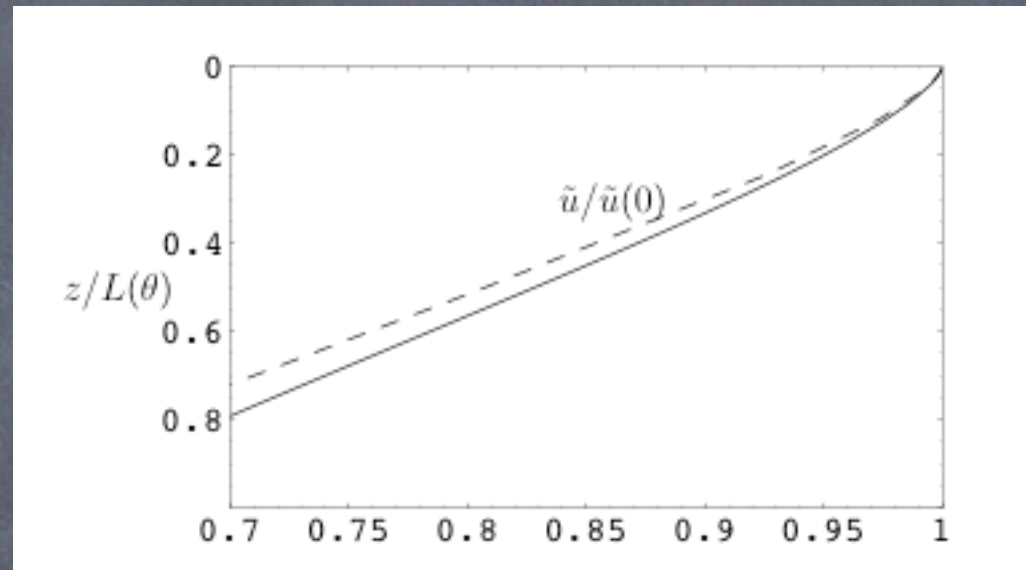
$$\frac{Q_{heap}}{D\sqrt{gD}} = \frac{(\sin(\theta) - \mu\cos(\theta))^{1/2}}{\left(1 - \frac{\mu_N}{\mu_T}(\tan(\theta) - \mu)\right)^{5/2}} \int_{\phi_m}^{\phi_M} \left(\frac{F^3}{\mu_T}\right)^{1/2} \frac{\partial F}{\partial \phi} \frac{d\phi}{\phi}$$



heap flows



Flow thickness $L(\theta)$

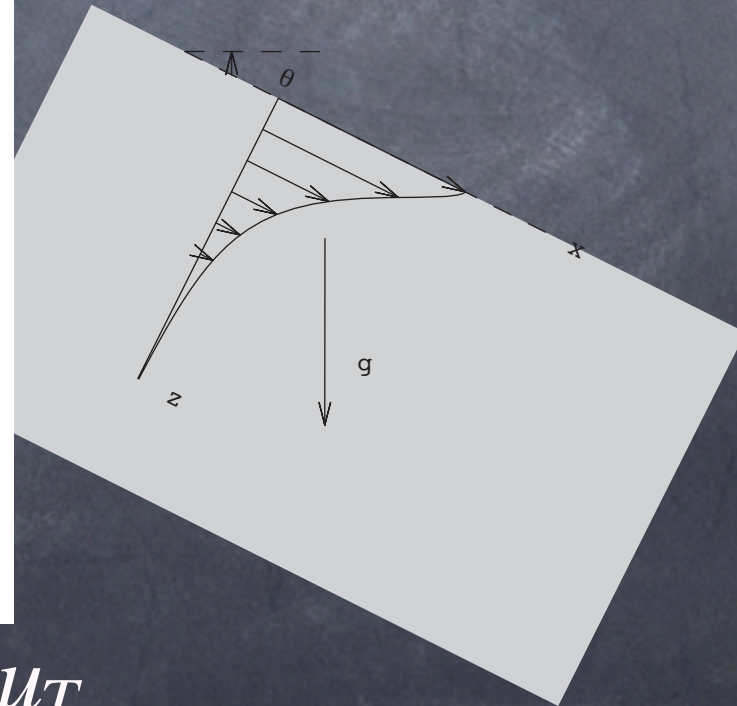
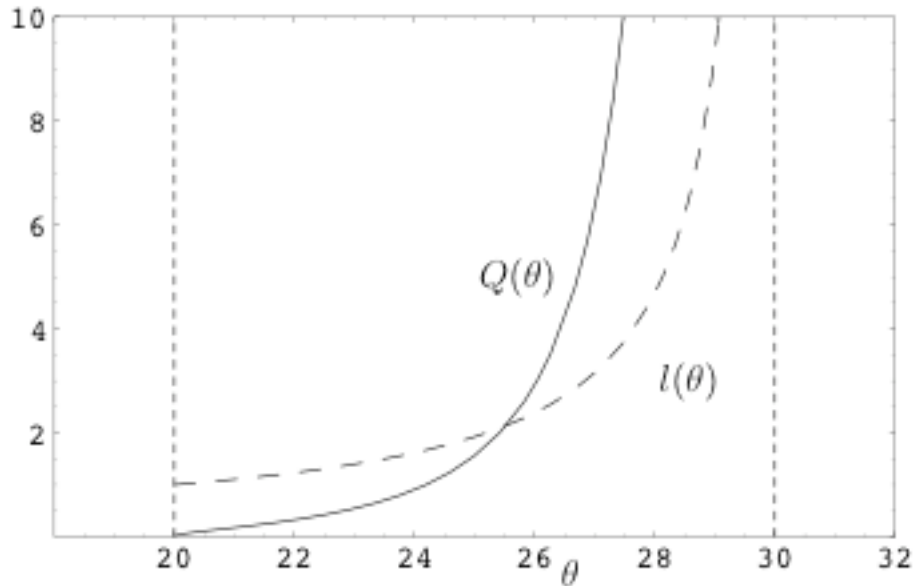


Relative velocity

Reduced compaction

Heap Flow

$$\frac{Q_{heap}}{D\sqrt{gD}} = \frac{(\sin(\theta) - \mu\cos(\theta))^{1/2}}{\left(1 - \frac{\mu_N}{\mu_T}(\tan(\theta) - \mu)\right)^{5/2}} \int_{\phi_m}^{\phi_M} \left(\frac{F^3}{\mu_T}\right)^{1/2} \frac{\partial F}{\partial \phi} \frac{d\phi}{\phi}$$



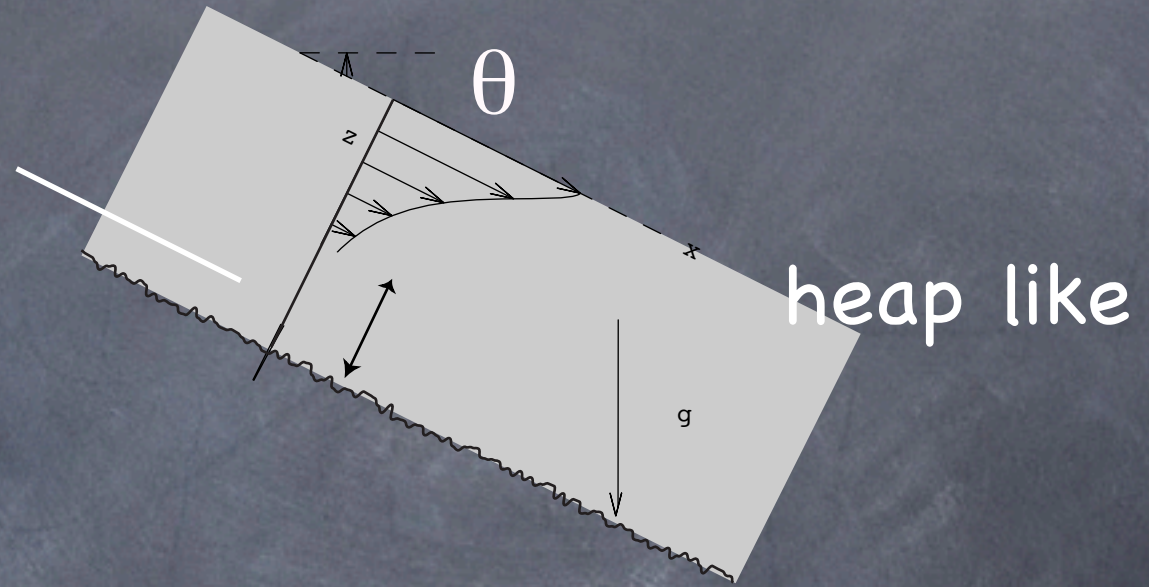
μ

$\mu + \mu_N/\mu_T$

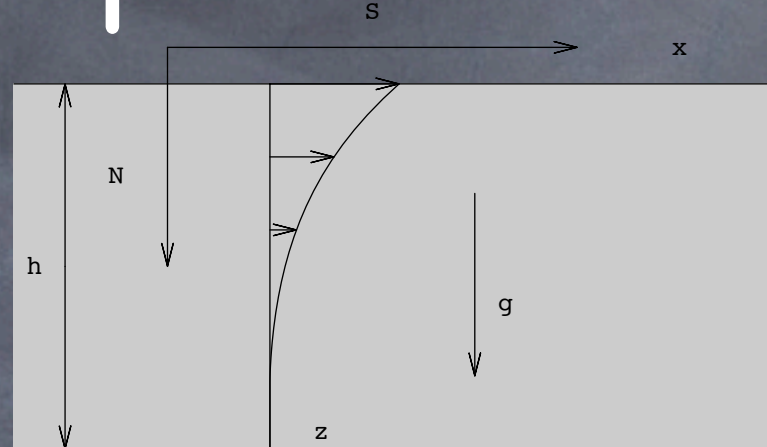
flows on rough inclined plates

θ and Q imposed

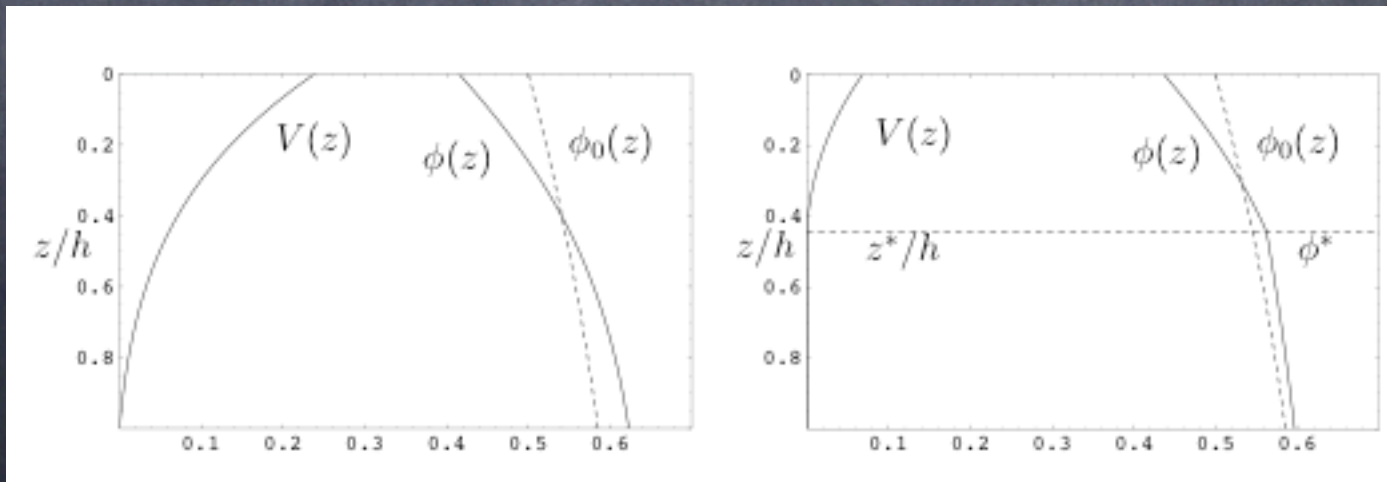
influence of roughness



plane shear

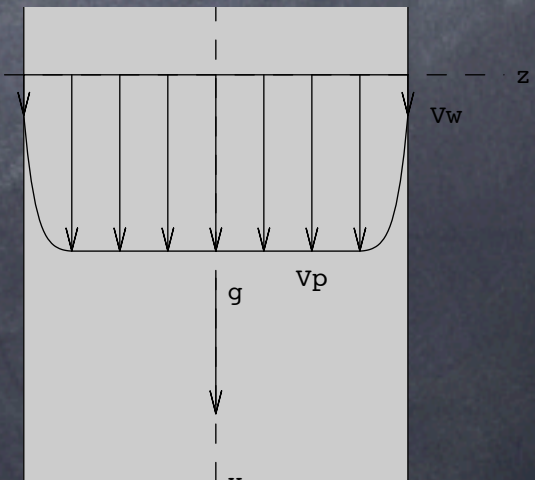
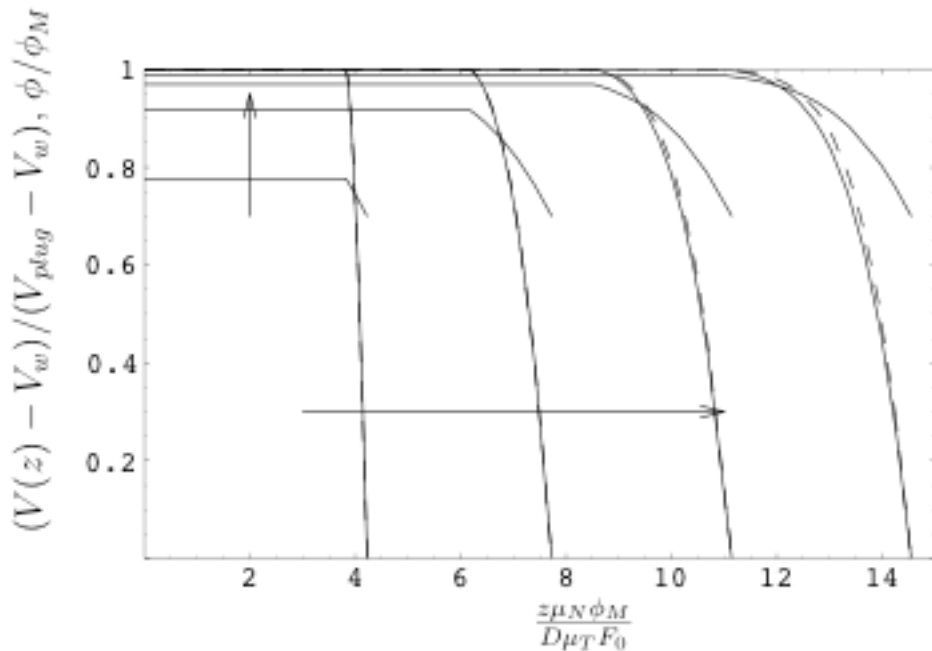


$$\rho D^2 \mu_T(\phi) \left(\frac{\partial V}{\partial z} \right)^2 = S - \mu(\phi) P(0) - \mu(\phi) \rho g \int_0^z \phi(\xi) d\xi$$



vertical chute flow

$$\rho D^2 \mu_T(\phi) \left(\frac{\partial V}{\partial z} \right)^2 = \rho g \int_0^z \phi(\xi) d\xi - \mu(\phi) P$$



h stop

- Just after stopping
- we know the compaction profile

$$0 = -\frac{\partial p}{\partial z} + \phi \rho_p g \cos \theta \quad p = P_0 \text{Log} \left(\frac{\phi_M - \phi_m}{\phi_M - \phi} \right)$$

$$\varphi(z) = 1 - \frac{1}{1 + \frac{\phi_m}{\phi_M} (e^{\frac{z}{L}} - 1)} \quad L/D = P_0 / (\phi_M \cos(\theta))$$

h stop

- We know the compaction profile $\varphi(z)$
- Da Cruz dependance of μ

$$\mu = \tan\theta_{max} - (\tan\theta_{max} - \tan\theta_{min}) \varphi$$

h stop

- We know the compaction profile $\varphi(z)$
- Da Cruz dependance of μ

$$\tan\theta = \tan\theta_{max} - (\tan\theta_{max} - \tan\theta_{min}) \varphi(h_{stop})$$

h stop

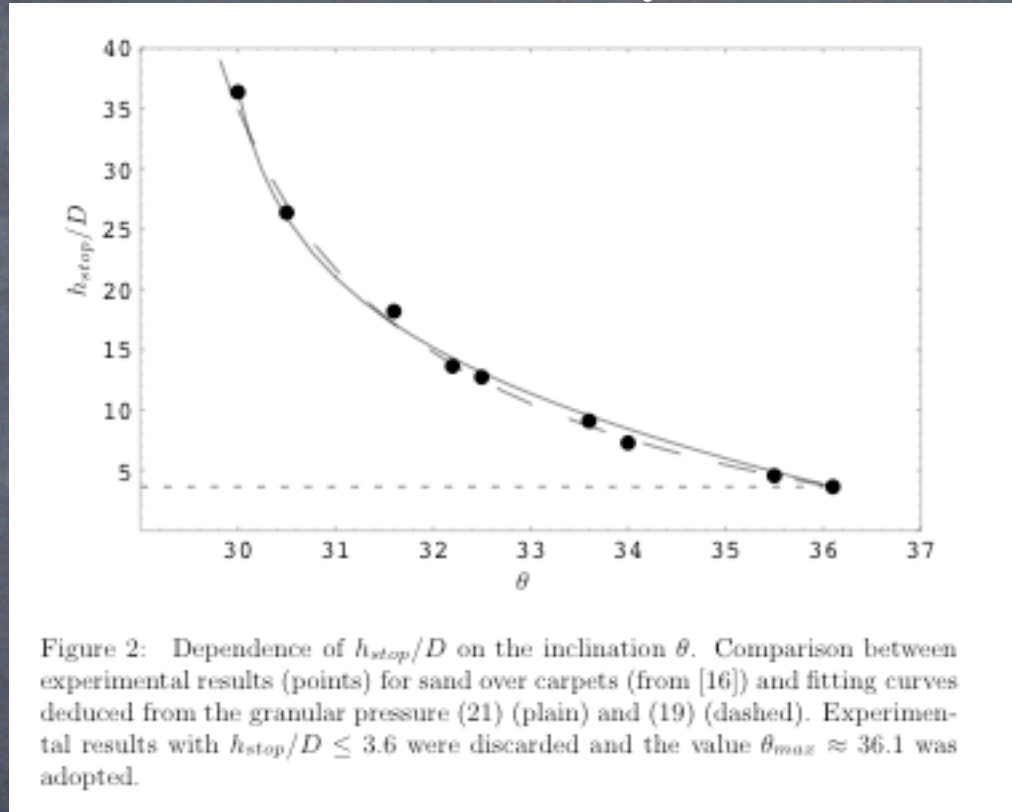
• as we have an explicit dependance

$$\frac{h_{stop}}{D} = \frac{P_0}{\phi_M \cos \theta} \text{Log} \left[1 + \frac{\phi_M \tan \theta_{max} - \tan \theta}{\phi_m \tan \theta - \tan \theta_{min}} \right] .$$

Pouliquen

$$\frac{h_{stop}}{D} = B \text{Log} \left[\frac{\tan \theta_{max} - \tan \theta_{min}}{\tan \theta - \tan \theta_{min}} \right] \text{ or } B \frac{\tan \theta_{max} - \tan \theta}{\tan \theta - \tan \theta_{min}}$$

h stop



$$\frac{h_{stop}}{D} = \frac{P_0}{\phi_M \cos \theta} \text{Log} \left[1 + \frac{\phi_M \tan \theta_{max} - \tan \theta}{\phi_m \tan \theta - \tan \theta_{min}} \right].$$

exp. from Da Cruz PhD

summary

- Local non local continuum description
- Blend of "old" ideas: Savage, Bagnold...
- Granular pressure
- some simple examples
- h stop
- perspectives?
 - changing the relations (F , μ ...)
 - introducing time?
 - ω near the boundary
- closure relation for Saint-Venant...

